Research Engineer • Implemented a 360 surround view monitoring system from four cameras around a car and perspective projection from fisheye

image (front/rear/left/right views, wheel views) which deployed success on VinFast E34. Technical based on camera intrinsic, extrinsic calibration, 3D object model, blending image 🕒

• Research in 3D Computer Vision: 3D reconstruction, 3D Point Cloud Object Detection and Segmentation, 360 view from multi

- Implemented calibration algorithms: Intrinsic camera, Extrinsic fisheye cameras-vehicle coordinate system(Ego), LiDAR-Camera, auto-calibration
- Implemented algorithms for mapping pixel index between Fisheye \leftrightarrow Perspective image. Estimate distance between vehicle coordinate system(Ego) to object based on calibration
- Auto Parking: Support build Occupancy Grid Map (OGM) from four cameras, researched path planning method
- Researched and applied CV, ML/DL techniques to develop 3DOD from LiDAR Point Cloud

AI Research Resident

- Research topic: 3D Point Cloud Segmentation, 3D Medical Image Segmentation
- Proposed a 3D Point Cloud method for 3D voxel medical image segmentation dataset
- Mentors: Dr. Binh-Son Hua

VCCorp

AI Engineer

- Implemented a classification system using RNN/LSTM model that can predict the category, detect depraved content/violence in videos on social media
- Implemented a VIP (very important person) detection system on videos

FPT Software	HCMC, Vietnam
AI Intern	Mar 2017 - May 2018
• Implemented a 3D medical Image Segmentation model, analysis, processing, and visualization of 3D image	ge data
• Implemented a object detection model for broken products when passing on conveyor belts in industrial	plants

PUBLICATIONS

Point-Unet: A Context aware Point-based Neural Network for Volumetric Segmentation MICCAI 2021 Ngoc-Vuong Ho, Tan Nguyen, Gia-Han Diep, Ngan Le, Binh-Son Hua

PROJECTS

Self-driving car Aug 2017 Implemented of mini-self-driving cars, running in real environment Using machine learning to detect lanes, traffic signs, and obstructions, thereby making decisions about speed, and steering angle \square Jul 2018

Document Layout Analysis

Implemented a segmentation model for the layout of the Vietnamese, and English document images (with respect to the magazine). Identify and localize areas of text, tables, charts and images along with their respective descriptions 🖸 Segmentation of Lungs from Chest X-Ray Mar 2019

Implemented an automatic lung segmentation systems for chest X-ray images. The system helps assess the health status of patients. Achieved an accuracy of over 98% \square

Honors & Awards

Fully Funded 2 years Masters Scholarships at UARK	2023
MICCAI 2021 Student Travel Award 盲	2021
HackerRank Certificates Problem Solving (Basic)	2020
Southeast Asia Machine Learning School in Indonesia 🖹	2019
The Mini-course "Statistical learning: bagging, boosting, SVM, introduction to neural network" 🖹	2019
Top 10/176 in the Document Layout Analysis - Cinnamon AI Marathon \blacksquare	2019
Top $8/876$ in the Digital race Driverless in 2017 -2018 by FPT Corporation	2018

TECHNICAL SKILLS

Programming: C/C++, Python, MATLAB, CUDA(basic), Parallel computing

Frameworks & Tools: Pytorch, TensorFlow, Unix/Linux, OpenCV, OpenGL(Basic), LATEX, Docker, ROS, Blender, Git Database: SQL, ETL Data Modeling, Kafka

EDUCATION

Vuong Ho

University of Arkansas

M.S in Computer Science. GPA: 4.0/4.0 (until present) University of Information Technology

B.S in Computer Science. GPA: 3.4/4.0 (8.1/10.0)

EXPERIENCE

Research assistant

views VinAI

University of Arkansas, USA

Arkansas, USA

HCMC, Vietnam

HCMC. Vietnam

Mar 2021 - Jun 2023

Apr 2020 - Mar 2021

HCMC, Vietnam

Jun 2019 - Apr 2020

Agu 2016 - Nov 2020

Jun 2023 - Present

J + 1(479) 301 - 1016✓ vvuonghn@gmail.com **☆** vvuonghn.github.io in vvuonghn

Jun 2023 - May 2025 (expected)